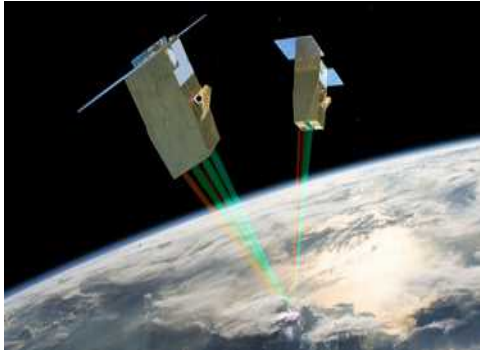




La mission C³IEL

Cluster for Cloud evolution Climate and Lightning

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C. Price⁵, D. Ricard⁶, A. Rimboud¹, Y. Schechner⁴, Y. Yair⁷,
C. Cheymol⁸, A. Deschamps⁸, A. Frid⁹, L. Gillot⁸, A. Kaidar⁹, and S. Aviad¹⁰**

¹LOA, France | ²The Hebrew University of Jerusalem, Israel | ³Laero, France

⁴Viterbi Faculty of Electrical Engineering Technion, Israel | ⁵Tel Aviv University, Israel

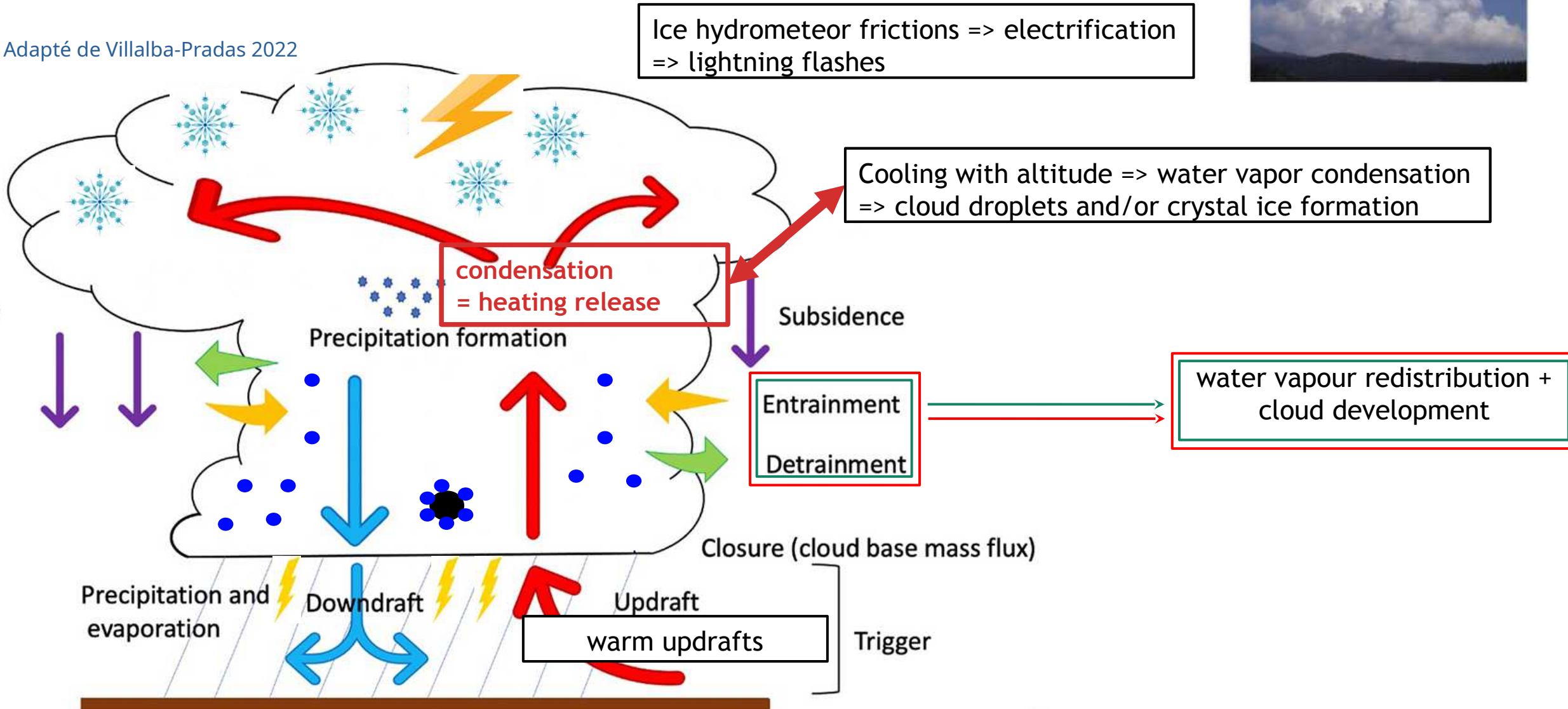
⁶CNRM, France | ⁷Reichman University, Israel | ⁸CNES, France

⁹Asher Space Research Institute, Israel | ¹⁰ISA, Israel

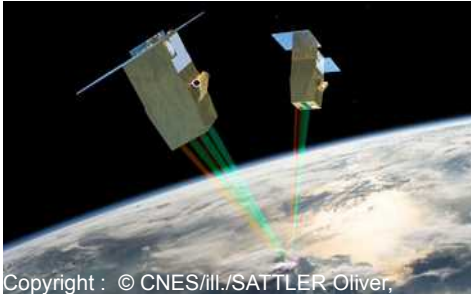
Convective clouds are complex systems



Adapté de Villalba-Pradas 2022



Caractéristiques des instrument

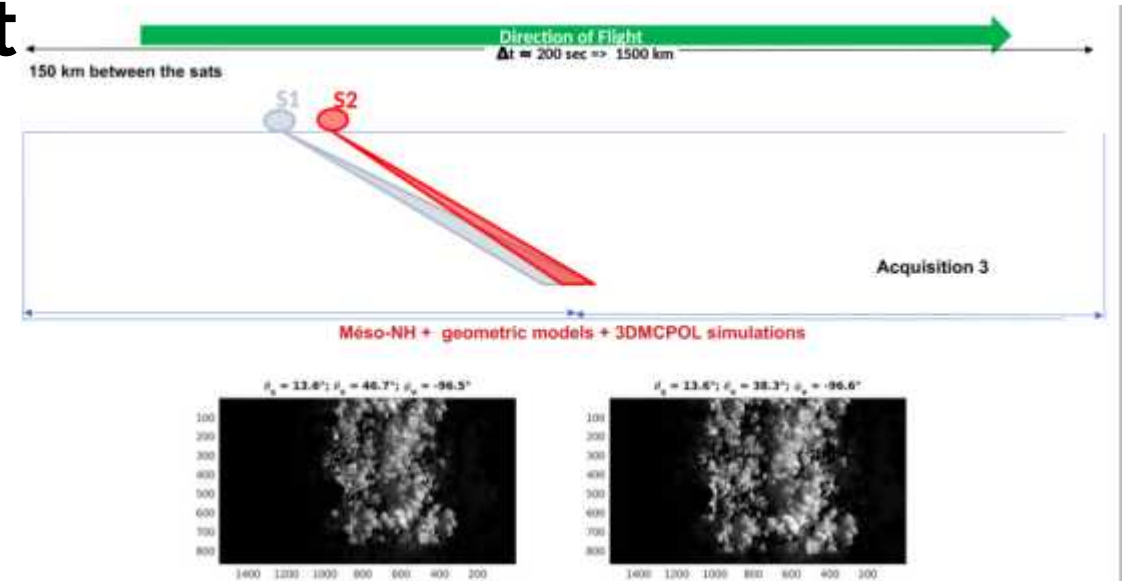


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https://videothèque.cnes.fr/index.php?urlaction=doc&id_doc=37976&rang=1&id_panier

2 synchronized satellites with :

Instrument	Characteristics	Variable	Targeted uncertainties
CLOUD (Day)	Visible imager at 647.5nm $\Delta x_{\text{nadir}} = 17 \text{ m}$ $\Delta t = 20 \text{ s}$ during 200s FOV = 80 km x 45km	Cloud envelop developpment velocity	1-2 m.s ⁻¹ over 200s
WV (Day)	SWIR imagers at 1.04, 1.13 and 1.37 μm $\Delta x_{\text{nadir}} = 125 \text{ m}$ $\Delta t = 20 \text{ s}$ during 200s FOV = 80 km x 64km	Integrated water vapor content around clouds + water vapor vertical profile	few kg.m ⁻²
LOIP (Day and night)	Visible imager at 777.4 nm $\Delta x_{\text{nadir}} = 140 \text{ m}$; $\Delta t = 15 \text{ ms}$ FOV = 360 km x 302 km Photometer at 777.4, 337 and 391 nm FOV = ~360 km diameter sampling at 20 kHz	Spatial and temporal lightning activity	70 to 90% of detection efficiency



Orbit : ascending node orbit at 1:30

Day orbit : 4 sequences of 11 acquisitions of 2 cloudy scenes (images)

Night orbit (LOIP) : continuous measurement during 1200s (20 min)

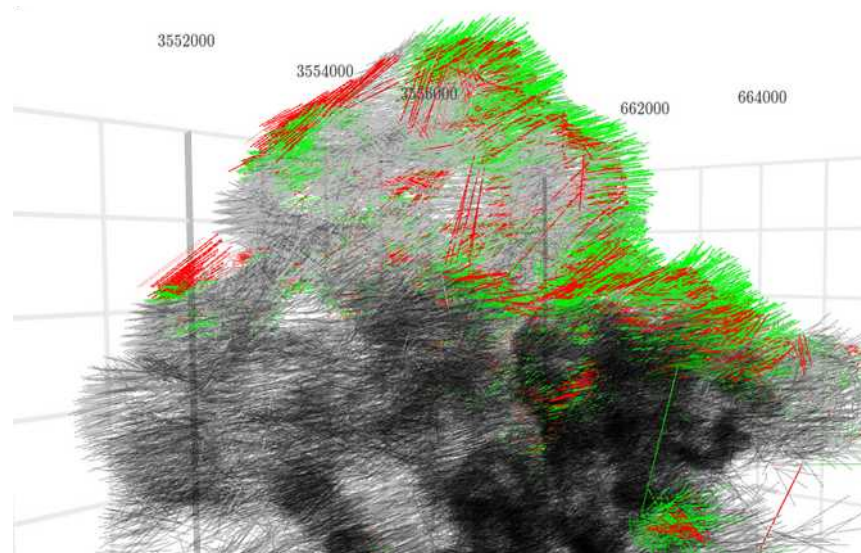
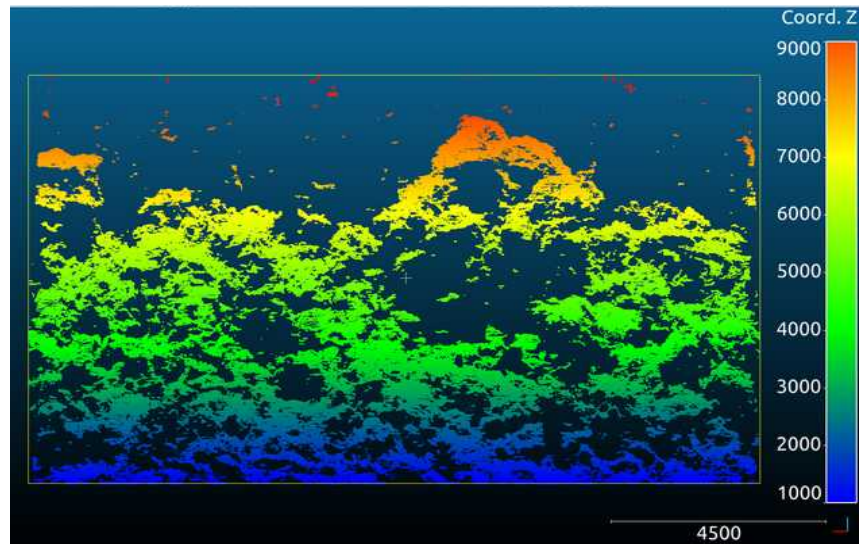
Sun-synchronous orbit with local time at the tropics between 12:00 and 14:00 PM with a preferred time at 13:30 pm and a maximum drift of one hour, only toward a later local time (+1h)

Launch scheduled for 2028

CLOUD : Enveloppe et vitesse de développement du nuage par stéréo-restitution

Instrument	Characteristics	Variable	Targeted uncertainties
CLOUD (Day)	Visible imager at 647.5nm $\Delta x_{\text{nadir}} = 17 \text{ m}$ $\Delta t = 20\text{s}$ during 200s FOV = 80 km x 45km	Cloud envelop development velocity	1-2 m.s ⁻¹ over 200s

L2A : 3D points de l'enveloppe du nuage **L2B : vitesse de développement de l'enveloppe**



+
**L3 : vitesse moyenne
de sommets
nuageux sur 200s**

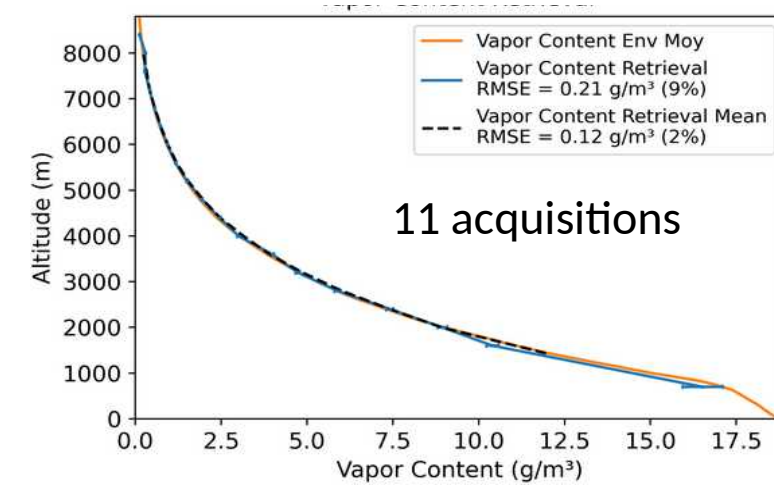
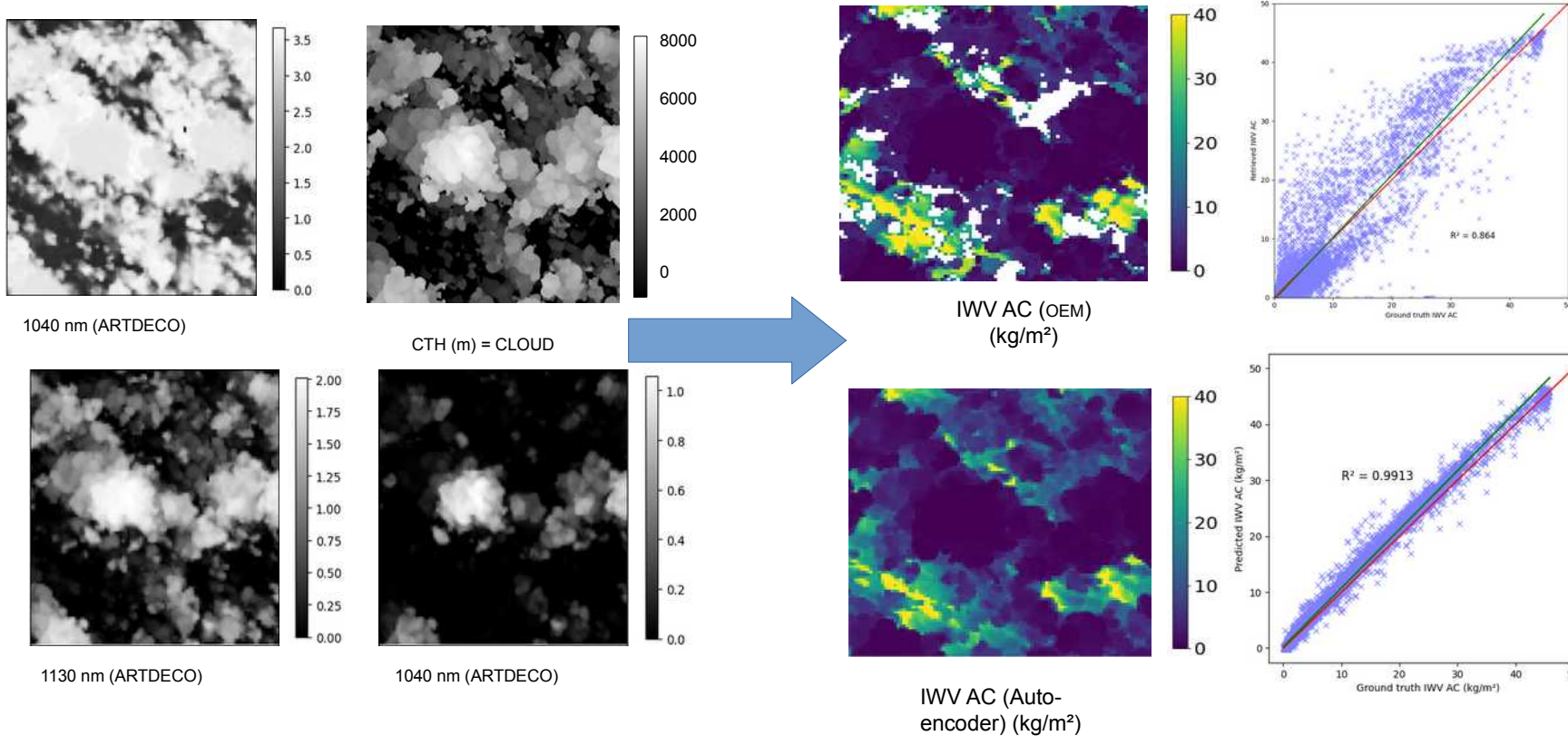
Black vectors: Ground estimation velocity vectors.
Red vectors: Velocity vectors from stereo-restitution
Green vectors: Ground estimation vectors (originally plotted in black),
close to the red stereo-restituted vectors.

WV : restitution de la vapeur d'eau autour des nuages

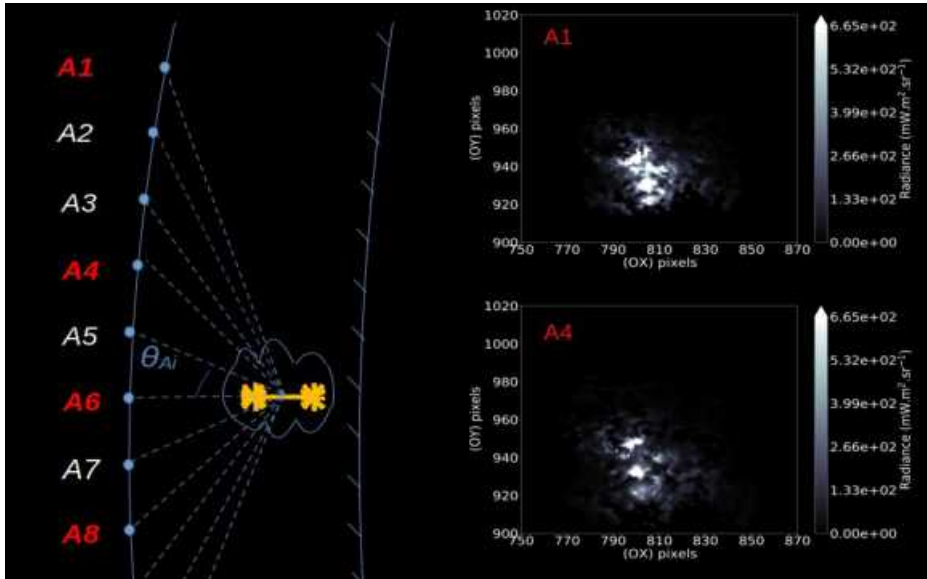
Instrument	Characteristics	Variable	Targeted uncertainties
WV (Day)	SWIR imagers at 1.04, 1.13 and 1.37 μm $\Delta x_{\text{nadir}} = 125 \text{ m}$ $\Delta t = 20\text{s}$ during 200s FOV = 80 km x 64km	Integrated water vapor content around clouds + water vapor vertical profile	few kg.m^{-2}

L2 : contenu intégré au-dessus des nuages

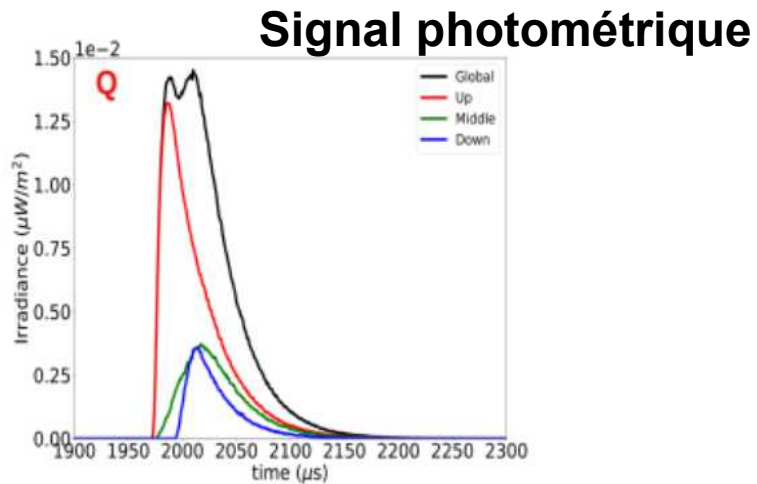
L3 : Profil moyen de la scène nuageuse



LOIP : Observation de l'activité électrique

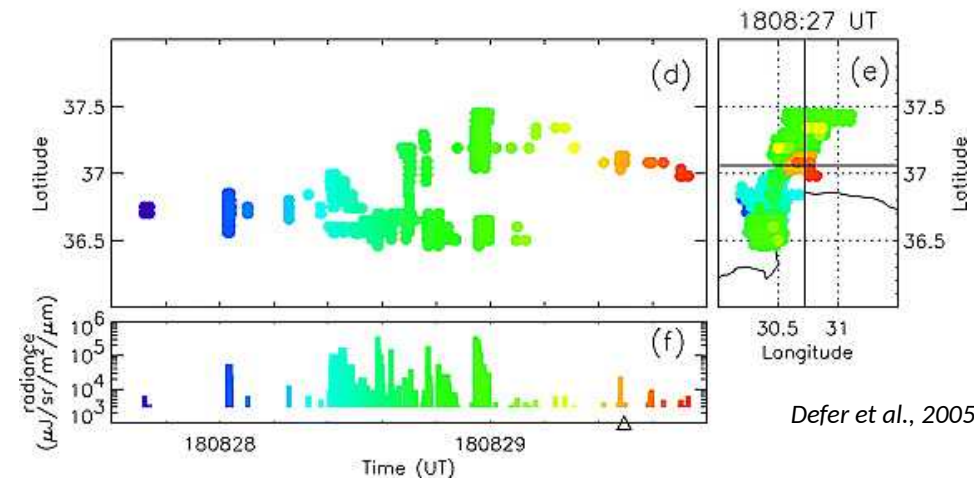
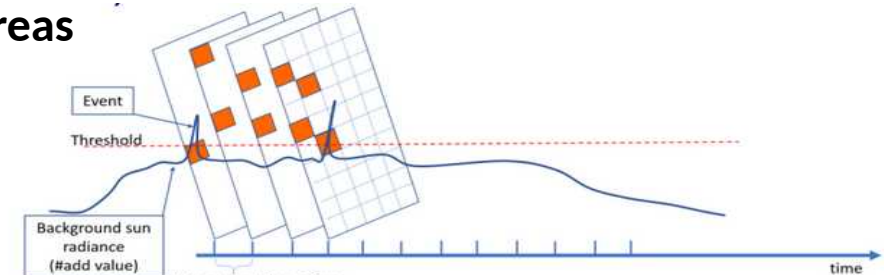


Realistic numerical simulation of the optical lightning signal
(Rimboud et al., in preparation)



Instrument	Characteristics	Variable	Targeted uncertainties
LOIP (Day and night)	Visible imager at 777.4 nm $\Delta x_{\text{nadir}} = 140 \text{ m}$; $\Delta t = 15 \text{ ms}$ FOV = 360 km x 302 km Photometer at 777.4, 337 and 391 nm FOV = ~360 km diameter sampling at 20 kHz	Spatial and temporal lightning activity	70 to 90% of detection efficiency

L2A : Illuminated pixels are merged together to form a group, and groups in flashes, and flashes in areas



Defer et al., 2005



=

**New observations of
convective clouds,
their environments and the
associated lightning activity**

Launch in 2028 !

Merci pour votre attention !

